

Efficient tomography of quantum optical Gaussian processes probed with a few coherent states

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An arbitrary quantum-optical process (channel) can be completely characterized by probing it with coherent states using the recently developed coherent-state quantum process tomography (QPT) [Lobino *et al.*, *Science* **322**, 563 (2008)]. In general, precise QPT is possible if an infinite set of probes is available. Thus, realistic QPT of infinite-dimensional systems is approximate due to a finite experimentally-feasible set of coherent states and its related energy-cut-off approximation. We show with explicit formulas that one can completely identify a quantum optical Gaussian process just with a few different coherent states without approximations like the energy cut-off. For tomography of multimode processes, our method exponentially reduces the number of different test states, compared with existing methods.

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I. INTRODUCTION

One of the basic problems of quantum physics is to predict the evolution of a quantum system under certain conditions. For an isolated system with a known Hamiltonian, the evolution is characterized by a unitary operator determined by the Schrödinger equation. However, the system may interact with its environment, and the total Hamiltonian of the system plus the environment is in general not completely known. The evolution can then be regarded as a “black-box process” [1–3] which maps the input state into an output state. An important problem here is how to characterize an unknown process by testing the black-box with some specific input states, which is referred to as quantum process tomography (QPT) (for reviews see Refs. [4, 5]).

QPT can be understood as the tomography of a quantum channel since any physical operation describing the dynamics of a quantum state can be considered as a channel [6]. By contrast, the goal of quantum state tomography (QST) is the reconstruction of an unknown state (i.e., its density matrix) by a series of measurements on multiple copies of the state (for a review see Ref. [4]). Both QPT and QST are essential tools in quantum engineering and quantum information processing.

A few methods for QPT were developed including the standard QPT [1, 2], ancilla-assisted QPT [3, 7–9], direct characterization of quantum dynamics [10, 11], and coherent-state QPT [12]. There are dozens of proposals and experimental realizations of QPT for systems

with a few qubits. These include the estimation of quantum optical gates [8, 11, 13–19], liquid nuclear-magnetic-resonance gates [20–22], superconducting gates [23–28] (for a review see Ref. [29]) and other solid-state gates [30–32], ion-trap gates [33, 34], or the estimation of the dynamics of atoms in optical lattices [35]. By contrast, there are only a very few experimental demonstrations of QPT for infinite-dimensional systems (see, e.g., Ref. [12]).

Any physical process can be described by a completely positive map ε . Such a process is fully characterized if the evolution of any input state ρ_{in} is predictable: $\rho_{\text{out}} = \varepsilon(\rho_{\text{in}})$. In general, QPT is very difficult to implement in high-dimensional spaces, and, more challengingly, in an infinite-dimensional space, such as a Fock space [9, 12]. Recently, Ref. [12] showed QPT in a Fock space for continuous variable (CV) states. Two conclusions can be drawn [12]: (i) If the output states of *all* coherent input states are known then one can predict the output state of any input state; (ii) By taking the photon-number-cut-off (or energy cut-off) approximation, one can then characterize an unknown process with a finite number of different input coherent states (CSs).

It is an interesting question to identify an exact QPT with finite coherent states. If the process is completely unknown then QPT with finite coherent states is impossible. However, if some of the constraints of the quantum process are known then QPT can be simplified and, thus, effective. In quantum optical process, Gaussian maps are the most common. In this article we show that if a certain quantum process is known to be Gaussian then an exact QPT can be performed with only a few different coherent states.

It is worth noting that there is some analogy between

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QPT and QST, especially for quantum optical Gaussian processes (channels) [6, 36] and Gaussian states [37, 38]. This analogy can be seen, e.g., by comparing correlations between observables encoded in the covariance matrices, which completely describe a Gaussian object (either a quantum state or process). Thus, tomographies of quantum Gaussian systems are effectively finite-dimensional with their covariance matrix having a physical meaning analogous to a finite-dimensional density matrix.

As has been shown in Ref. [3], QPT can be performed with two-mode squeezed vacuum (TMSV) for any unknown process. However, TMSV are not so easy to manipulate in practice. Especially, because this involves quantum tomography of entangled states, which is not an easy task.

Here, we show that based on existing results [3], by using the standard quantum-optical Husimi Q -representation, one can perform QPT with only a few CSs without entangled ancillas for quantum optical Gaussian processes. The method described here has several advantages. First, it presents explicit formulas *without* any approximations, such as the photon-number-cut-off approximation. Second, it requires only a few different states to characterize a process, rather than *all* CSs. Third, for multimode Gaussian process tomography, the number of input CSs increases *polynomially* with the number of modes, rather than exponentially. Fourth, it uses the Husimi Q -functions only, which is always well-defined for *any* state without any higher order singularities in the calculation.

The paper is organized as follows: In Sec. II, the above-mentioned QPT *without* ancillas is proposed for single-mode Gaussian processes. A simple illustrative example of the method is discussed in Sec. II.A. A generalization of our QPT for a multi-mode case is presented in Sec. III. For comparison, we review the existing results about QPT *based on* entangled ancillas in Appendix A.

II. ANCILLA-FREE GAUSSIAN PROCESS TOMOGRAPHY WITH A FEW COHERENT STATES

Here we present the main result of this paper, which is an efficient tomography of Gaussian processes probed with only a *few* single-mode coherent states without the assistance of ancillas.

As shown in Ref. [12], if we only use CSs in the test, the tomography of an unknown process in Fock space requires tests with *all* CSs. Though this problem can be solved by taking the photon-number-cut-off approximation, in a quantum-optical process associated with intense light, one still needs a huge number of different CSs for the test. Here we show that the most important process in quantum optics, the Gaussian process [6, 36], can be *exactly* characterized with only a few CSs in the test.

A Gaussian process maps Gaussian states into Gaus-

sian states [39]. Therefore the Husimi Q -function of the operator ρ_ε must be Gaussian:

$$Q_{\rho_\varepsilon}(Z_a^*, Z_b^*, Z_a, Z_b) = \exp(c_0 + L + L^\dagger + S + S^\dagger + S_0), \quad (1)$$

where

$$\begin{aligned} L &= (\Gamma_a, \Gamma_b) \begin{pmatrix} Z_a \\ Z_b \end{pmatrix}, \\ S &= \frac{1}{2}(Z_a, Z_b)X \begin{pmatrix} Z_a \\ Z_b \end{pmatrix}, \\ S_0 &= (Z_a^*, Z_b^*)Y \begin{pmatrix} Z_a \\ Z_b \end{pmatrix}, \\ X &= X^T = \begin{pmatrix} X_{aa} & X_{ab} \\ X_{ba} & X_{bb} \end{pmatrix}, \\ Y &= Y^\dagger = \begin{pmatrix} Y_{aa} & Y_{ab} \\ Y_{ba} & Y_{bb} \end{pmatrix}. \end{aligned}$$

Before testing the map, all these are unknowns. The normally-ordered form of the density operator ρ_ε is

$$\rho_\varepsilon =: Q_{\rho_\varepsilon}(a^\dagger, b^\dagger, a, b) : \quad (2)$$

corresponding to Eq. (1) but with variables (Z_a^*, Z_b^*, Z_a, Z_b) replaced by $(a^\dagger, b^\dagger, a, b)$. The normal order notation $: \dots :$ indicates that any term inside it is reordered by placing the creation operator in the left. For example, $: aba^\dagger b^\dagger a := a^\dagger b^\dagger a^2 b$.

The output state from any single-mode input coherent state $|u\rangle$ (in mode b) is

$$\rho_u = \text{tr}_a [(|u^*\rangle\langle u^*|)_a \otimes I \cdot \rho_\varepsilon], \quad (3)$$

where ρ_ε is given by Eq. (2). Its Husimi Q -function is

$$\begin{aligned} Q_{\rho_u}(Z_b^*, Z_b) &= Q_{\rho_\varepsilon}(u, Z_b^*, u^*, Z_b) \\ &= \exp(c_u + L_u + L_u^\dagger + R + R^\dagger + R_0), \end{aligned} \quad (4)$$

where

$$\begin{aligned} L_u &= (\Gamma_b + u^* X_{ab} + u Y_{ab}) Z_b, \\ R &= Z_b X_{bb} Z_b / 2, \quad R_0 = Z_b^* Y_{bb} Z_b, \end{aligned}$$

and c_u is determined by c_0 , Γ_a , X_{aa} , and Y_{aa} . Explicitly,

$$c_u = c_0 + \text{Re} (2\Gamma_a u^* + u^* X_{aa} u^* + u Y_{aa} u^*). \quad (5)$$

The quadratic functional terms (R, R^\dagger, R_0) in the exponent in Eq. (4) are independent of u ; these terms must be the same for the output states from any input CSs. Therefore, these can be known by testing the map with one coherent state. Thus, we do not need to consider these terms below.

Now suppose that we test the process with six different CSs, $|\alpha_i\rangle$, and $i = 1, 2, \dots, 6$. Assume also that the detected Husimi Q -function of the output states is

$$Q_{\rho_{\alpha_i}}(Z_b^*, Z_b) = \exp(c_i + D_i + D_i^\dagger + R + R^\dagger + R_0), \quad (6)$$

where $D_i = d_i Z_b$ is the detected (hence known) linear term. We note that there are available efficient methods of Gaussian QST based on homodyne detection, which enable the estimation of the Wigner function or, equivalently, the Husimi Q -function for Gaussian states [38]. According to Eq. (4), the Q -function of the output state from the initial state $|\alpha_i\rangle$ of mode b must be

$$Q_{\rho_{\alpha_i}}(Z_b^*, Z_b) = Q_{\rho_\varepsilon}(\alpha_i, Z_b^*, \alpha_i^*, Z_b). \quad (7)$$

Therefore, we can derive self-consistent equations by using the detected data from ρ_{α_i} and setting $u = \alpha_i$ in Eq. (4):

$$L_i = D_i, \quad c_{\alpha_i} = c_i, \quad (8)$$

where L_i , c_{α_i} are just L_u , c_u , respectively, after setting $u = \alpha_i$ in Eqs. (4)-(5); D_i and c_i are known from tests. Explicitly,

$$L_i = (\Gamma_b + \alpha_i^* X_{ab} + \alpha_i Y_{ab}) Z_b. \quad (9)$$

The first part of Eq. (8) causes:

$$K \cdot (\Gamma_b, X_{ab}, Y_{ab})^T = d, \quad (10)$$

where

$$K = \begin{pmatrix} 1 & \alpha_1^* & \alpha_1 \\ 1 & \alpha_2^* & \alpha_2 \\ 1 & \alpha_3^* & \alpha_3 \end{pmatrix}, \quad d = \begin{pmatrix} d_1 \\ d_2 \\ d_3 \end{pmatrix}.$$

There are three unknowns (Γ_b , X_{ab} , and Y_{ab}) with three equations now. We find

$$(\Gamma_b, X_{ab}, Y_{ab})^T = K^{-1}d. \quad (11)$$

If the Gaussian process is known to be trace-preserving then Eq. (11) completes the tomography: up to a numerical factor, we can deduce all the output states of the other input CSs, $|\alpha_i\rangle$, for $i = 4, 5, 6$. The term c_i can be fixed through normalization, which is determined by the quadratic and linear functional terms in the exponent of the Q -functions. Knowing these $\{c_i\}$, one can construct ρ_ε completely as shown below.

For any map, c_i can be known from tests with $|\alpha_i\rangle$, for $i = 1, 2, \dots, 6$. We then have

$$J \cdot (c_0, \Gamma_a, \Gamma_a^*, X_{aa}, X_{aa}^*, Y_{aa})^T = c, \quad (12)$$

where

$$J = \begin{pmatrix} 1 & \alpha_1^* & \alpha_1 & \frac{1}{2}\alpha_1^{*2} & \frac{1}{2}\alpha_1^2 & |\alpha_1|^2 \\ 1 & \alpha_2^* & \alpha_2 & \frac{1}{2}\alpha_2^{*2} & \frac{1}{2}\alpha_2^2 & |\alpha_2|^2 \\ 1 & \alpha_3^* & \alpha_3 & \frac{1}{2}\alpha_3^{*2} & \frac{1}{2}\alpha_3^2 & |\alpha_3|^2 \\ 1 & \alpha_4^* & \alpha_4 & \frac{1}{2}\alpha_4^{*2} & \frac{1}{2}\alpha_4^2 & |\alpha_4|^2 \\ 1 & \alpha_5^* & \alpha_5 & \frac{1}{2}\alpha_5^{*2} & \frac{1}{2}\alpha_5^2 & |\alpha_5|^2 \\ 1 & \alpha_6^* & \alpha_6 & \frac{1}{2}\alpha_6^{*2} & \frac{1}{2}\alpha_6^2 & |\alpha_6|^2 \end{pmatrix}, \quad c = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \end{pmatrix},$$

for the second part of Eq. (8). Thus

$$(c_0, \Gamma_a, \Gamma_a^*, X_{aa}, X_{aa}^*, Y_{aa})^T = J^{-1}c. \quad (13)$$

Theorem: Given K and J defined by Eqs. (10)-(12) then the QPT of any single-mode Gaussian process in Fock space can be performed with six input CSs, when $\det K \neq 0$ and $\det J \neq 0$. The QPT of any trace-preserving single-mode Gaussian process in Fock space can be executed with three input CSs, when $\det K \neq 0$.

For example, one can simply choose $\alpha_1 = 0$, $\alpha_2 = 1$, $\alpha_3 = i$, $\alpha_4 = -1$, $\alpha_5 = -i$, and $\alpha_6 = 1+i$. One finds

$$\begin{aligned} c_0 &= c_1, \quad \Gamma_b = d_1, \\ \Gamma_a &= \frac{1}{4} (c_2 + ic_3 - c_4 - ic_5), \\ X_{ab} &= \frac{1}{2} [-(1+i)d_1 + d_2 + id_3], \\ Y_{ab} &= \frac{1}{2} [-(1-i)d_1 + d_2 - id_3], \\ Y_{aa} &= \frac{1}{4} (c_2 + c_3 + c_4 + c_5) - c_1, \\ X_{aa} &= \frac{1}{4} [c_2 - c_3 + c_4 - c_5 + 2i(c_1 - c_2 - c_3 + c_6)], \end{aligned} \quad (14)$$

where $\{d_i\}$ and $\{c_i\}$ are defined in Eq. (6).

A. Example: Output state of a beam-splitter process

As a check of our conclusions, we calculate the output state of a beam-splitter (BS) process as shown in Fig. 1. The BS has input modes b and c and output modes b' and c' . Regarding this as a black-box process, the only input is mode b and the only output is mode b' . We set mode c to be the vacuum. The BS transforms the creation operators of modes b and c by:

$$U_{\text{BS}}(b^\dagger, c^\dagger) U_{\text{BS}}^{-1} = (b^\dagger, c^\dagger) M_{\text{BS}}, \quad (15)$$

where $M_{\text{BS}} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$. If we test such a process with a coherent state $|\alpha_i\rangle$, we shall find $\rho_{\alpha_i} = |\alpha_i \cos \theta\rangle \langle \alpha_i \cos \theta|$. Comparing this with Eq. (6), we have $d_i = \alpha_i^* \cos \theta$ and $c_i = -|\alpha_i \cos \theta|^2$. Using Eqs. (11)-(13), we find

$$\begin{aligned} Y_{bb} &= -1, \quad X_{ab} = \cos \theta, \quad Y_{aa} = -\cos^2 \theta, \\ \Gamma_a &= \Gamma_b = Y_{ab} = X_{aa} = X_{bb} = c_0 = 0. \end{aligned} \quad (16)$$

Therefore

$$\rho_\varepsilon =: \exp(a^\dagger b^\dagger \cos \theta - a^\dagger a \cos^2 \theta - b^\dagger b + ab \cos \theta) :. \quad (17)$$

With this we can predict the output state of *any* input state, for example the squeezed coherent state (squeezed displaced vacuum)

$$|\xi(r, Z)\rangle = \exp\left[\frac{r}{2}(b^2 - b^{\dagger 2})\right] \exp(Zb^\dagger - Z^*b) |0\rangle, \quad (18)$$

where r is real. According to Eq. (A8),

$$\rho_\xi = \text{tr}_a [(\xi(r, Z^*)\langle \xi(r, Z^*)|)a \otimes I_b \cdot \rho_\varepsilon]. \quad (19)$$

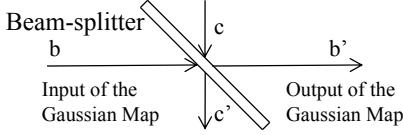


FIG. 1: Gaussian map constructed by a beam-splitter. Here, we assume that the input mode c is in the vacuum.

As a result,

$$Q_{\rho_\xi}(Z_b^*, Z_b) = C \exp(\mathcal{H}_1 - \mathcal{H}_2 + \mathcal{H}_3 + \mathcal{H}_4), \quad (20)$$

where C is the normalization factor, and

$$\begin{aligned} \mathcal{H}_1 &= |Z_b|^2 (\tanh^2 r \sin^2 \theta - 1)/g, \\ \mathcal{H}_2 &= (Z_b^2 + Z_b^{*2}) \tanh r \cos^2 \theta/(2g), \\ \mathcal{H}_3 &= Z_b \cos \theta (Z^* - Z \tanh r \sin^2 \theta)/(g \cosh r), \\ \mathcal{H}_4 &= Z_b^* \cos \theta (Z - Z^* \tanh r \sin^2 \theta)/(g \cosh r), \end{aligned}$$

and $g = 1 - \tanh^2 r \sin^4 \theta$. This is the same result obtained from direct calculations using Eq. (15).

III. EFFICIENT MULTIMODE-GAUSSIAN QPT

Multimode Gaussian QPT has many important applications. For example, it applies to a complex linear optical circuit with BSs, squeezers, homodyne detections, linear losses, Gaussian noises, and so on. Consider now a Gaussian process acting on a k -mode input state (in modes b_1, b_2, \dots, b_k), with outcome also a k -mode state. Even though other methods [12] can also be extended to the multimode case, the number of input states required there increases exponentially with the number of modes k , because the number of ket-bra operators $|\{n_i\}\rangle\langle\{m_i\}|$ in Fock space increases exponentially with k . As shown below, the number of input states in our method increases *polynomially*.

A k -mode QPT can be tested with k -mode CSs, if the process is Gaussian. The main Eqs. (11)-(13) still hold after redefining the notations there. First, Γ_a , Γ_b , u , α_i , d_i , Z_a , and Z_b are now k -mode vectors. For example,

$$\begin{aligned} |\alpha_i\rangle &= |\alpha_{i1}, \alpha_{i2}, \dots, \alpha_{ik}\rangle, \\ d_i &= (d_{i1}, d_{i2}, \dots, d_{ik}), \quad Z_b = (Z_{b1}, Z_{b2}, \dots, Z_{bk}), \end{aligned}$$

and so on. Following Eq. (1), \mathcal{X}_{xy} is now a $k \times k$ matrix, for $\mathcal{X} = X$ or Y with $x = a, b$; $y = a, b$. We still apply Eqs. (11)-(13) to calculate $\{\Gamma_b, X_{ab}, Y_{ab}\}$ and $\{\Gamma_a, X_{aa}, Y_{aa}\}$, respectively, but keep in mind that the matrices K , J and symbols d , c are now redefined. There are $(2k+1)k$ unknowns in $(\Gamma_B, X_{ab}, Y_{ab})$. We need $(2k+1)$ different CSs of k -mode to fix these unknowns. Now we have

$$K = \begin{pmatrix} 1 & \alpha_1^* & \alpha_1 \\ 1 & \alpha_2^* & \alpha_2 \\ \vdots & \vdots & \vdots \\ 1 & \alpha_k^* & \alpha_k \end{pmatrix}, \quad (21)$$

which is a $(2k+1) \times (2k+1)$ matrix, since each α_i here is a k -mode row vector. Moreover, d is here a $(2k+1) \times k$ matrix as $d^T = (d_1^T, d_2^T, \dots, d_{2k+1}^T)$, with $d_i = (d_{i1}, d_{i2}, \dots, d_{ik})$. Similarly,

$$J = \begin{pmatrix} 1 & \alpha_1^* & \alpha_1 & \frac{1}{2}\alpha_1^{*2} & \frac{1}{2}\alpha_1^2 & |\alpha_1|^2 \\ 1 & \alpha_2^* & \alpha_2 & \frac{1}{2}\alpha_2^{*2} & \frac{1}{2}\alpha_2^2 & |\alpha_2|^2 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & \alpha_N^* & \alpha_N & \frac{1}{2}\alpha_N^{*2} & \frac{1}{2}\alpha_N^2 & |\alpha_N|^2 \end{pmatrix}, \quad (22)$$

which is now a $N \times N$ matrix, and $N = (k+1)(2k+1)$, since α_i^2 and $|\alpha_i|^2$ here are row vectors of $\alpha_i^2 = (E_{i1}, E_{i2}, \dots, E_{ik})$ and $|\alpha_i|^2 = (\tilde{E}_{i1}, \tilde{E}_{i2}, \dots, \tilde{E}_{ik})$, and each element of E_{im} (or \tilde{E}_{im}) is a vector with $(k-m+1)$ modes (or k modes), as

$$\begin{aligned} E_{im} &= (\alpha_{im}^2, \alpha_{im}\alpha_{i,m+1}, \alpha_{im}\alpha_{i,m+2}, \dots, \alpha_{im}\alpha_k, \alpha_k^2), \\ \tilde{E}_{im} &= (\alpha_{im}\alpha_{i1}^*, \alpha_{im}\alpha_{i2}^*, \dots, \alpha_{im}\alpha_{i,k-1}^*, \alpha_{im}\alpha_{ik}^*). \end{aligned}$$

Obviously, c is a column vector with N elements. Therefore we conclude with this:

Corollary: Any k -mode Gaussian QPT can be performed with $(k+1)(2k+1)$ different CSs of k -mode; or with $(2k+1)$ different CSs of k -mode if the process is trace preserving.

IV. CONCLUSIONS

In summary, we have presented explicit formulas for the tomography of quantum optical Gaussian processes probed with only a few different coherent states. We have reduced the problem of Gaussian QPT to Gaussian QST, for which efficient methods are experimentally available [38]. We have extended our results to multimode Gaussian QPT and demonstrated that the number of test states required increases only polynomially with the number of modes.

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Appendix A: Ancilla-assisted quantum process tomography

Here, we review the existing result of the ancilla-assisted QPT with TMSV [3] to show some similarities but also crucial differences in comparison to our proposal of ancilla-free QPT.

A TMSV is defined by $|\chi(q)\rangle = c_q \exp(qa^\dagger b^\dagger)|00\rangle$, where $c_q = \sqrt{1-q^2}$, and q is real. The (unnormalized) maximally-entangled state here is

$$|\Phi^+\rangle = \lim_{q \rightarrow 1} \exp(qa^\dagger b^\dagger)|00\rangle = \sum_{k=0}^{\infty} |kk\rangle, \quad (\text{A1})$$

where a^\dagger (b^\dagger) is the creation operator for mode a (b). Note that entanglement is not required for the ancilla-assisted QPT, but makes it more efficient. In particular, the use of the maximally-entangled states can make the QPT experimentally optimal with regard to perfect non-local correlations [8].

Assume now that the black box process acts only in mode b of the bipartite state $|\chi(q)\rangle$. After the process, we obtain a two-mode state Ω_q . One can define the projection operator

$$T(q) = c_q \exp[(\ln q)a^\dagger a], \quad (\text{A2})$$

which has the property [40]:

$$T(q)(a, a^\dagger) T^{-1}(q) = (a/q, qa^\dagger). \quad (\text{A3})$$

The TMSV $|\chi(q)\rangle$ can be written as

$$|\chi(q)\rangle = T(q) \otimes I |\Phi^+\rangle. \quad (\text{A4})$$

According to Eq. (A4), we have

$$\Omega_q = T(q) \otimes I \cdot \rho_\varepsilon \cdot T(q) \otimes I, \quad (\text{A5})$$

where $\rho_\varepsilon = I \otimes \varepsilon(|\Phi^+\rangle\langle\Phi^+|)$. Naturally,

$$\rho_\varepsilon = T^{-1}(q) \otimes I \cdot \Omega_q \cdot T^{-1}(q) \otimes I. \quad (\text{A6})$$

We now also formulate the output state of any single-mode input state $|\psi(\{c_k\})\rangle = \sum_k c_k |k\rangle$ of mode b . Obviously it can be written as

$$\begin{aligned} (|\psi\rangle\langle\psi|)_b &= {}_a\langle\psi^*|\Phi^+\rangle\langle\Phi^+|\psi^*\rangle_a \\ &= \text{tr}_a (|\psi^*\rangle\langle\psi^*| \otimes I \cdot |\Phi^+\rangle\langle\Phi^+|), \end{aligned} \quad (\text{A7})$$

and $|\psi^*\rangle_a = \sum_k c_k^* |k\rangle_a$ is a single-mode state for mode a (sometimes we omit the subscript a or b for simplicity). We obtain the output state

$$\begin{aligned} \rho_\psi &= {}_a\langle\psi^*|\rho_\varepsilon|\psi^*\rangle_a = \text{tr}_a (|\psi^*\rangle\langle\psi^*| \otimes I \cdot \rho_\varepsilon) \\ &= \text{tr}_a [|\psi^*(\{c_k/q^k\})\rangle\langle\psi^*(\{c_k/q^k\})| \otimes I \cdot \Omega_q] \\ &= {}_a\langle\psi^*(\{c_k/q^k\})|\Omega_q|\psi^*(\{c_k/q^k\})\rangle_a. \end{aligned} \quad (\text{A8})$$

More explicit expressions can be obtained by using the Husimi Q -function. If the single-mode input state in

mode b is a coherent state $|\alpha\rangle$, the output state then becomes

$$\rho_\alpha = \langle\alpha^*|\rho_\varepsilon|\alpha^*\rangle = \langle\alpha^*|T^{-1}(q) \otimes I \cdot \Omega_q \cdot T^{-1}(q) \otimes I|\alpha^*\rangle. \quad (\text{A9})$$

Note that the state $|\alpha^*\rangle$ here is a single-mode coherent state in mode a . Using the property of $T(q)$ and the definition of CSs, $a|\alpha^*\rangle = \alpha^*|\alpha^*\rangle$, we easily find

$$T^{-1}(q) \otimes I |\alpha^*\rangle = \mathcal{N}_q(\alpha) |\alpha^*/q\rangle, \quad (\text{A10})$$

where the factor $\mathcal{N}_q(\alpha) = \exp[-|\alpha|^2(1-1/q^2)/2]/c_q$, and $|\alpha^*/q\rangle$ is a coherent state in mode a defined by $a|\alpha^*/q\rangle = (\alpha^*/q)|\alpha^*/q\rangle$. Thus, the output state of mode b is

$$\rho_\alpha = |\mathcal{N}_q(\alpha)|^2 {}_a\langle\alpha^*/q|\Omega_q|\alpha^*/q\rangle_a. \quad (\text{A11})$$

Assume the Husimi Q -function for Ω_q is $Q_{\Omega_q}(Z_a^*, Z_b^*, Z_a, Z_b)$. According to its definition,

$$Q_{\Omega_q}(Z_a^*, Z_b^*, Z_a, Z_b) = \langle Z_a, Z_b | \Omega_q | Z_a, Z_b \rangle, \quad (\text{A12})$$

where $|Z_a, Z_b\rangle$ is a two-mode coherent state defined by $(a, b)|Z_a, Z_b\rangle = (Z_a, Z_b)|Z_a, Z_b\rangle$. Hence the corresponding density operator is the following normally-ordered operator

$$\Omega_q =: Q_{\Omega_q}(a^\dagger, b^\dagger, a, b) :, \quad (\text{A13})$$

which is simply the operator functional obtained by replacing the variables (Z_a^*, Z_b^*, Z_a, Z_b) with $(a^\dagger, b^\dagger, a, b)$ in the Q -function given by Eq. (A12), analogously to Eq. (2). Therefore, using Eq. (A11) and the normally-ordered form of Ω_q , we have the following simple form for the Husimi Q -function

$$Q_{\rho_\alpha}(Z_b^*, Z_b) = |\mathcal{N}_q(\alpha)|^2 Q_{\Omega_q}(\alpha/q, Z_b^*, \alpha^*/q, Z_b) \quad (\text{A14})$$

of the output state ρ_α . Eqs. (A11)-(A14) are the explicit expressions of the output state for the input of *any* coherent state $|\alpha\rangle$. According to Ref. [12], if we know the output states for all input CSs then we know the output states of all states in Fock space. In this approach, given any input state $|\psi\rangle$, we can write it in its linear superposition form in the coherent-state basis, and then obtain the Q -function of its output state by using Eq. (A14).

These results can be generalized for a multimode QPT. To apply the Jamiołkowski isomorphism [41], we consider k pairs of maximally-entangled states, each in modes $a_1, b_1, a_2, b_2, \dots, a_k, b_k$. Explicitly, $|\Phi^+\rangle = |\phi^+\rangle_1 |\phi^+\rangle_2 \dots |\phi^+\rangle_k$. Here $|\phi^+\rangle_i = \lim_{q \rightarrow 1} \exp(qa_i^\dagger b_i^\dagger)|00\rangle$ indicates a maximally-entangled state in modes a_i, b_i . Subspaces a and b each are now k -mode. Any state $|\psi\rangle$ in subspace b , can still be written in the form of Eq. (A7), with the new definitions for $|\psi\rangle$ and $|\Phi^+\rangle$. Using Eq. (A6), it is obvious that the output state of these k -pairs of TMSV fully characterizes the process.

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